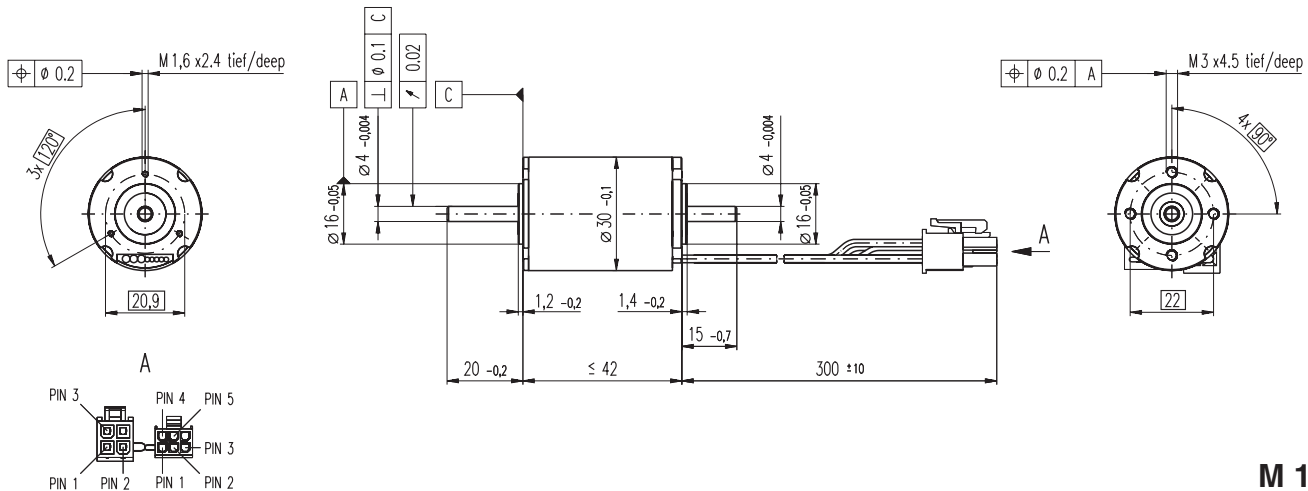


# EC-max 30 $\varnothing$ 30 mm, brushless, 40 Watt



- Stock program
- Standard program
- Special program (on request)

### Order Number

272766    272768    272769    272770

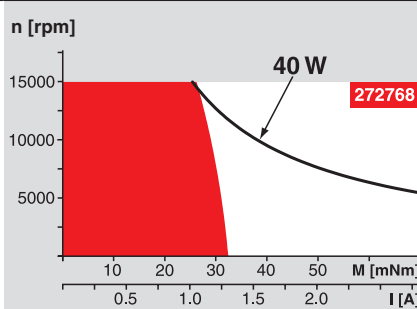
### Motor Data

Values at nominal voltage		272766	272768	272769	272770	
1	Nominal voltage	V	12.0	24.0	36.0	48.0
2	No load speed	rpm	8700	9270	9160	9270
3	No load current	mA	202	112	73.2	55.9
4	Nominal speed	rpm	6640	7210	7080	7190
5	Nominal torque (max. continuous torque)	mNm	35.0	34.3	33.9	34.0
6	Nominal current (max. continuous current)	A	2.85	1.50	0.976	0.743
7	Stall torque	mNm	153	160	154	157
8	Starting current	A	11.8	6.57	4.18	3.24
9	Max. efficiency	%	76	76	76	76
<b>Characteristics</b>						
10	Terminal resistance phase to phase	$\Omega$	1.01	3.65	8.61	14.8
11	Terminal inductance phase to phase	mH	0.088	0.31	0.713	1.24
12	Torque constant	mNm / A	12.9	24.3	36.8	48.6
13	Speed constant	rpm / V	738	393	259	197
14	Speed / torque gradient	rpm / mNm	57.8	59.1	60.6	59.9
15	Mechanical time constant	ms	6.66	6.81	6.98	6.90
16	Rotor inertia	gcm <sup>2</sup>	11.0	11.0	11.0	11.0

### Specifications

- Thermal data**
- 17 Thermal resistance housing-ambient 8.6 K / W
  - 18 Thermal resistance winding-housing 1 K / W
  - 19 Thermal time constant winding 3.12 s
  - 20 Thermal time constant motor 777 s
  - 21 Ambient temperature -20 ... +100°C
  - 22 Max. permissible winding temperature +155°C
- Mechanical data (preloaded ball bearings)**
- 23 Max permissible speed 15000 rpm
  - 24 Axial play at axial load < 6.0 N 0 mm
  - > 6.0 N 0.14 mm
  - 25 Radial play preloaded
  - 26 Max. axial load (dynamic) 5.5 N
  - 27 Max. force for press fits (static) 100 N
  - (static, shaft supported) 2000 N
  - 28 Max. radial loading, 5 mm from flange 25 N

### Operating Range



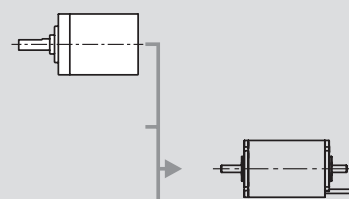
### Comments

- Continuous operation**  
In observation of above listed thermal resistance (lines 17 and 18) the maximum permissible winding temperature will be reached during continuous operation at 25°C ambient.  
= Thermal limit.
- Short term operation**  
The motor may be briefly overloaded (recurring).
- Assigned power rating**

- Other specifications**
- 29 Number of pole pairs 1
  - 30 Number of phases 3
  - 31 Weight of motor 165 g
- Values listed in the table are nominal.
- Connection Motor (Cable AWG 20)**
- |       |                 |       |
|-------|-----------------|-------|
| red   | Motor winding 1 | Pin 1 |
| black | Motor winding 2 | Pin 2 |
| white | Motor winding 3 | Pin 3 |
|       | N.C.            | Pin 4 |
- Connector Article number**
- Molex 39-01-2040
- Connection Sensors (Cable AWG 26)**
- |        |                                  |       |
|--------|----------------------------------|-------|
| yellow | Hall sensor 1                    | Pin 1 |
| brown  | Hall sensor 2                    | Pin 2 |
| grey   | Hall sensor 3                    | Pin 3 |
| blue   | GND                              | Pin 4 |
| green  | V <sub>Hall</sub> 4.5 ... 24 VDC | Pin 5 |
|        | N.C.                             | Pin 6 |
- Connector Article number**
- Molex 430-25-0600
- Wiring diagram for Hall sensors see page 27

### maxon Modular System

- 1 Planetary Gearhead  $\varnothing$ 32 mm
- 3 1.0 - 6.0 Nm
- Page 241



### Overview on page 16 - 21

- Encoder MR**  
128 - 1000 CPT,  
3 channels  
Page 258
- Encoder HEDL 5540**  
500 CPT,  
3 channels  
Page 266
- Brake AB 20**  
 $\varnothing$ 20 mm  
24 VDC, 0.1 Nm  
Page 306

- Recommended Electronics:**
- |             |          |
|-------------|----------|
| DECS 50/5   | Page 284 |
| DEC 50/5    | 285      |
| DECV 50/5   | 286      |
| DES 50/5    | 287      |
| EPOS 24/5   | 294      |
| EPOS2 50/5  | 295      |
| EPOS P 24/5 | 297      |
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